Accelerated lattice Boltzmann simulation using GPU and OpenACC with data management

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Abstract

We assess the performance of the combined Open Accelerator (OpenACC) programming standard and graphics processing unit (GPU) accelerator for lattice Boltzmann (LB) simulations of fluid flow, heat and mass transfer. By optimizing the data layout, minimizing the memory access frequency, and adjusting the number of gangs and vector length, we show that the enhanced parallel computations can result in orders of magnitude of speedup relative to the serial implementation of the LB algorithm. Based on such implementations, benchmark quality results are obtained with fine grid of $2049^2$ for both two-dimensional lid driven cavity flow with Reynolds number up to 7500, and double diffusive cavity flow with solute Rayleigh number up to $10^8$.

1. Introduction

The consistent demand for higher simulation accuracy and larger computing capability has driven the prosperous of high performance computing community [1]. During the past decades, the performance of central processing unit (CPU) microprocessor chip has been exponentially growing and follows the Moore’s law, which indicates that the chip’s performance will double every two years. As the microprocessor reduces its physical size to tens of nanometer, the Moore’s law seems nearing its end [2]. On the other hand, utilizing graphics processing unit (GPU) as computational accelerators has attracted great attention due to its combined tremendous computing power and superior memory bandwidth. For example, the memory bandwidth is 480 gigabyte per second (GB/s) and the peak double precision floating point performance can reach 2910 giga floating-point operations per second (GFLOPS) for the newest NVIDIA® Tesla® K80 GPU accelerator, which is an order of magnitude higher than that for the newest Intel® Core™ i7 CPU processor.

The lattice Boltzmann (LB) method, originated from cellular automata and also derived from the Boltzmann kinetic theory, has been proven to be a promising tool for simulating fluid flows and associated transport phenomena. It is based on mesoscopic kinetic equations describing the evolution of fluid parcels, and boundary conditions can be easily implemented, thus making it suitable for simulating complex fluid systems, such as gas-liquid two-phase flow [3–6], particulate flow [7–10], flow in porous media [11–13], and so on. More importantly, the locality nature of extensive computations makes the LB method favorable for massively parallel programming, which is crucial for practical engineering applications.

Parallel computing framework utilizing GPUs includes Open Computing Language (OpenCL), Compute Unified Device Architecture (CUDA), and Open Accelerator (OpenACC). OpenCL is an open standard for programming heterogeneous platforms consisting of CPUs and GPUs. It specifies C/C++ programming language, and programmers must explicitly manage the way that a problem is decomposed to the hardware. CUDA works with programming languages such as C, C++ and Fortran. Although it reduces the effort in graphics programming compared to OpenCL, it only runs on NVIDIA’s graphics card. These two programming standards require substantial changes in the original code, thus threatening the code correctness, portability, and maintainability. OpenACC is a high level, platform independent, and directive based programming standard being jointly developed by NVIDIA, Cray, PGI, and CAPS. Following hints provided by programmers as annotations to the original code, compute intensive calculations are offloaded to the accelerator device to utilize the superior computing capabilities of the accelerator.

A number of studies have been conducted to utilize the computing power of GPUs to accelerate LB simulations [14–19]. However, most of the previous studies were based on CUDA acceleration, which may pose severe restriction on the target hardware. For example, Sailfish [20], a free computational fluid dynamics solver based on lattice Boltzmann method, serves as a reference GPU
implementation. It is based on CUDA/OpenCL programming standard and implements LB models for single- and multi-component fluid flows. To the best of our knowledge, very few implementations of LB method incorporating OpenACC acceleration have been described in the literature [21]. In Ref. [21], a D2Q37 lattice model was adopted for the two-dimensional simulation of convective turbulence; while in our work, the most widely used D2Q9 lattice model and D2Q5 lattice model will be adopted for the two-dimensional simulation of laminar fluid flows and heat/mass transfer, respectively. The benefit of using simpler lattice model is that memory storage is reduced, while there is no loss of simulation accuracy for the laminar flow simulations. The immature of OpenACC application in LB simulation may be mainly due to the perception that simplicity and portability of OpenACC come at a price of degrading parallel performance. This motivates us to address implementation issues when using OpenACC to accelerate LB simulations, i.e., optimizing the data layout to meet the requirement of coalescence memory access pattern, minimizing the memory access frequency by fusing the collision and streaming subroutine, and adjusting number of gangs and vector length to maximize utilize specific hardware architecture. We show that ultra-high computational performance can be achieved with proper implementations, including simulations involving coupled fluid flow, heat and mass transfer processes. By adopting OpenACC accelerated LB simulations, highly refined computations can be made. To demonstrate this point, three two-dimensional benchmark problems, namely, lid driven cavity problem, buoyancy driven cavity problem, and double diffusive cavity problem, with the grid size up to 2049² will be presented.

2. Numerical method

2.1. LB model for fluid flow

Fluid flows described by the incompressible Navier-Stokes equations can be written as

\[ \nabla \cdot \mathbf{u} = 0 \]  

\[ \frac{\partial \mathbf{u}}{\partial t} + \nabla \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u} \]  

where \( \mathbf{u} \) is the fluid velocity, \( \rho \) is the fluid density, \( p \) is the pressure, and \( \nu \) is the kinematic viscosity.

In LB method, to solve Eqs. (1a) and (1b), the evolution equation of density distribution function based on D2Q9 lattice model can be written as

\[ f_i(x + \mathbf{e}_i \delta_t, t + \delta_t) - f_i(x, t) = -(\mathbf{M}^{-1} \mathbf{S})_{ij} \left[ \mathbf{m}_j(x, t) - \mathbf{m}_{ij}^{eq}(x, t) \right] \]  

where \( f_i \) is the density distribution function, \( t \) is the time, \( \delta_t \) is the time step, \( \mathbf{x} \) is the fluid parcel position, and \( \mathbf{e}_i \) is the discrete velocity along the \( i \)th direction. To approximate incompressible flows and minimize the round-off error, we only consider density fluctuation \( \delta \rho \) in various parts of equilibrium following Luo et al. [22]. Then, the equilibrium moments \( \mathbf{m}_{eq} \) is given by

\[ \mathbf{m}_{eq} = \left[ \begin{array}{c} \delta \rho \mathbf{1} + \frac{3}{\rho_0} (\mathbf{J}_s^2 + \mathbf{J}_r^2), \delta \rho - \frac{3}{\rho_0} (\mathbf{J}_s^2 + \mathbf{J}_r^2), \mathbf{J}_s, \mathbf{J}_r, -\mathbf{J}_s, -\mathbf{J}_r, -\mathbf{J}_r, -\mathbf{J}_s, \mathbf{1} \end{array} \right]^T \]  

The relaxation matrix is given by \( \mathbf{S} = \text{diag}(s_1, s_2, s_3, s_4, s_5, s_6, s_7, s_8, s_9) \), where the relaxation parameters are given as \( s_1 = s_2 = s_3 = s_4 = s_5 = s_6 = s_7 = s_8 = 1/\tau_f, s_9 = 8(2\tau_f - 1)/(8\tau_f - 1) \), and \( \tau_f \) is determined by the kinematic viscosity of the fluids. The density variation \( \delta \rho \) and velocity \( \mathbf{u} \) are obtained from

\[ \delta \rho = \sum_{i=0}^{8} f_i, \quad \mathbf{u} = \sum_{i=0}^{8} \mathbf{e}_i f_i \]  

and the kinetic viscosity \( \nu \) is given by

\[ \nu = \frac{1}{3} c^2 \left( \tau_f - \frac{1}{2} \right) \delta_t \]  

where \( c = \delta_s/\delta_t \) is lattice constant, and \( c = \delta_s = \delta_t = 1 \) is adopted in this work.

2.2. LB model for fluid flow and heat transfer

In incompressible thermal flows, temperature variation will cause density variation thus resulting in buoyancy effect. Following the Boussinesq approximation, the temperature can be treated as a passive scalar, and its influence to the velocity field is through the buoyancy term [23,24]. Then, the governing equations can be written as

\[ \nabla \cdot \mathbf{u} = 0 \]  

\[ \frac{\partial \mathbf{u}}{\partial t} + \nabla \mathbf{u} = -\frac{1}{\rho_0} \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{g} \beta_T(T - T_0) \mathbf{y} \]  

\[ \frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \kappa \nabla^2 T \]  

where \( T \) is the temperature, \( \beta_T \) is the thermal expansion coefficient, and \( \kappa \) is the thermal diffusivity. \( g \) is the gravity value, and \( \mathbf{y} \) is unit vector in the vertical direction. \( \rho_0 \) and \( T_0 \) are reference density and temperature, respectively.

In LB method, to solve Eqs. (6a) and (6b), the evolution equation of density distribution function is similar to Eq. (2) except with the addition of forcing term, which is written as

\[ f_i(x + \mathbf{e}_i \delta_t, t + \delta_t) - f_i(x, t) = -(\mathbf{M}^{-1} \mathbf{S})_{ij} \left[ \mathbf{m}_j(x, t) - \mathbf{m}_{ij}^{eq}(x, t) \right] + \delta \mathbf{F}_i \]  

where \( \mathbf{F}_i \) is the forcing term in velocity space, and is given by

\[ \mathbf{F} = \mathbf{M}^{-1} \left( 1 - \frac{S}{2} \right) \mathbf{M} \]  

and the term \( \mathbf{MF} \) is given by

\[ \mathbf{MF} = [0, 6 \mathbf{u}, \mathbf{F}, -6 \mathbf{u}, \mathbf{F}, \mathbf{F}_x, -\mathbf{F}_x, -\mathbf{F}_y, 2(\mathbf{u}_x \mathbf{F}_y - \mathbf{u}_y \mathbf{F}_x), (\mathbf{u}_x \mathbf{F}_y + \mathbf{u}_y \mathbf{F}_x)]^T \]  

where \( \mathbf{F} = g \beta_T(T - T_0) \mathbf{y} \). The density variation \( \delta \rho \) and velocity \( \mathbf{u} \) are obtained from

\[ \delta \rho = \sum_{i=0}^{8} f_i, \quad \mathbf{u} = \sum_{i=0}^{8} \mathbf{e}_i f_i + \frac{1}{2} \mathbf{F} \]  

To solve Eq. (6c), the evolution equation of temperature distribution function based on D2Q5 lattice model can be written as

\[ g_i(x + \mathbf{e}_i \delta_t, t + \delta_t) - g_i(x, t) = -(\mathbf{N}^{-1} \mathbf{Q})_{ij} \left[ \mathbf{n}_j(x, t) - \mathbf{n}_{ij}^{eq}(x, t) \right] \]  

where \( g_i \) is the temperature distribution function. The equilibrium moments \( \mathbf{n}_{eq} \) is given by

\[ \mathbf{n}_{eq} = \left[ T, \ u_T, \ \nu T, \ a_T T, \ 0 \right]^T \]  

where \( a_T \) is a constant determined by the thermal diffusivity as

\[ a_T = 20 \sqrt{3} \chi - 4 \]  

The relaxation matrix is given by \( \mathbf{Q} = \text{diag}(0, q_c, q_c, q_c, q_c) \), where the relaxation parameters are given as \( q_c = 3 - \sqrt{3} \) and \( q_c = 4 \sqrt{3} - 6 \).
The temperature $T$ is obtained from

$$T = \sum_{i=0}^{4} g_i$$

(14)

2.3. LB model for fluid flow, heat transfer and mass transfer

In addition to temperature variation, concentration variation will also cause density variation, thus resulting in buoyancy effect. Analogous to the Boussinesq approximation, the concentration can also be treated as a passive scalar, and its influence to the velocity field is through the buoyancy term [25]. Then, the governing equations can be written as

$$\nabla \cdot \mathbf{u} = 0$$

(15a)

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho_0} \nabla p + \nu \nabla^2 \mathbf{u} + g \beta \rho (T - T_0) \mathbf{y} + g \beta (C - C_0) \mathbf{y}$$

(15b)

$$\frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \kappa \nabla^2 T$$

(15c)

$$\frac{\partial C}{\partial t} + \mathbf{u} \cdot \nabla C = D \nabla^2 C$$

(15d)

where $C$ is the concentration, $\beta$ is the concentration expansion coefficient, and $D$ is the mass diffusivity. $\rho_0, T_0$ and $C_0$ are reference density, temperature, and concentration, respectively.

In LB method, to solve Eqs. (15a) and (15b), the evolution equation of density distribution function is the same as Eq. (7), and $\mathbf{F}$ in Eq. (9) is given as $F = g \beta \rho (T - T_0) \mathbf{y} + g \beta (C - C_0) \mathbf{y}$; to solve Eq. (15c), the evolution equation of temperature distribution function is the same as Eq. (11); to solve Eq. (15d), the evolution equation of concentration distribution function based on D2Q5 lattice model can be written as

$$h_i (\mathbf{x} + \mathbf{e}_i \Delta t, t + \Delta t) - h_i (\mathbf{x}, t) = -\frac{1}{\mathbf{n}^T \mathbf{Q} \mathbf{n}} \left[ n_i (\mathbf{x}, t) - n_i^{(eq)} (\mathbf{x}, t) \right]$$

(16)

where $h_i$ is the concentration distribution function. Here, the equilibrium moments $n^{(eq)}$ is given by

$$\mathbf{n}^{(eq)} = [ C, uC, vC, qC, 0]^T$$

(17)

where $a_i$ is a constant determined by the mass diffusivity as

$$a_i = 20\sqrt{3}D - 4$$

(18)

The relaxation matrix is given by $\mathbf{Q} = \text{diag} (0, q_c, q_c, q_c, q_c)$, where the relaxation parameters are given as $q_c = 3 - \sqrt{3}$ and $q_r = 3 - \sqrt{6}$.

The temperature $C$ is obtained from

$$C = \sum_{i=0}^{4} h_i$$

(19)

3. OpenACC implementation and optimization

3.1. GPU programming using OpenACC

CPUs are optimized for low latency access to cached data, while GPUs are optimized for data parallelism and hide latency with intensive computations. In OpenACC parallel execution model, both computation and data are offloaded from the CPU host to the GPU accelerator, so that the combined tremendous computing power and superior memory bandwidth of GPU can be utilized. To ensure the correctness of the code employing OpenACC acceleration, an incremental approach to accelerate the code should be taken. The first step is to assess the numerical algorithm and estimate the running time each subroutine takes. In LB method, the standard implementation consists of four subroutines: collision, streaming, bounce-back, and calculating macro variables as illustrated in Fig. 1. Among them, the collision subroutine takes the most computational time due to extensive updates of distribution function along nine directions in two-dimensional simulations or nineteen directions in three-dimensional simulations at a fluid node; in the streaming subroutine, the information of distribution function at a node is simply transferred to its neighboring, and there is no tedious mathematical computations; the bounce-back subroutine only works at the boundary nodes to mimic various boundary conditions; although the subroutine of calculating macro variables also takes effect at fluid nodes in the whole computational domain, its computational cost is much lower compared to the collision subroutine due to much simpler mathematical manipulations. The second step is to use OpenACC parallel loop directive to parallelize computational intensive loops. Thanks to the locality nature of LB method, the subroutines of collision and calculating macro variables completely use local node information. Although the streaming subroutine involves data transfer, the data dependence problem can be avoided by using two distribution functions for data swapping. The third step is to optimize data locality and minimize data transfer between CPU host and GPU accelerator through PCIe. After initializing the macroscopic field information (such as velocity $u$, density $\rho$, temperature $T$ and concentration $C$) and the mesoscopic distribution functions (such as density distribution function $f$, temperature distribution function $g$ and concentration distribution function $h$), they can be copied into GPU memory space, and only copied back to CPU until the end of iterations. This can be achieved by the data clauses including copy, copyin, copyout, and create. Otherwise, at each iterative step, all the data will be transferred between CPUs and GPUs by default, which may consume more time than the computation itself.

To characterize the parallel performance of LB implementation, we adopt the metrics of million lattice updates per second (MLUPS), which is defined as

$$\text{MLUPS} = \frac{\text{meshsize} \times \text{iterationsteps}}{\text{runtime} \times 10^6}$$

(20)

For a given mesh size, we fixed the iteration steps as 20,000, and measure the running time. Less running time results in higher MLUPS, which also means the better parallel performance. All the simulations in the present work use double-precision floating point arithmetic, which ensures the simulation accuracy.

Three benchmark problems, namely, lid driven cavity problem [26,27], buoyancy driven cavity problem [28,29], and double diffusive cavity problem [30,31] are adopted to investigate the parallel computing performance of OpenACC based LB simulation involving multiphysics processes. Fig. 2 shows the computing performance of utilizing OpenACC with the programming effort mentioned.

**Fig. 1.** Schematic illustration of LB flow chart.
above, and around 12–13 times speedup can be obtained comparing with the original code running on CPU. It is interesting to notice that the computing performance is much higher for the isothermal fluid flow problem than that for the coupled fluid flow, heat and mass transfer problem. This is because LB algorithm is memory bandwidth limited algorithm, and the usage of more global arrays to store distribution functions will appear as a limiting step. Specifically, we need three distribution functions $f$, $g$, and $h$ to store the information for flow field, temperature field, and concentration field in the double diffusive cavity problem. In contrast, only one distribution function $f$ is needed in the lid driven cavity problem. It should also be pointed out that, this is the most basic effort of porting to GPU platform, and we can further boost the parallel computing performance by applying the improvement strategies mentioned in Sections 3.2, 3.3 and 3.4.

3.2. Optimize data layout

Usually, in CPU based LB implementation, the data layout of distribution function belongs to array of structure (AoS) because CPUs can make use of cache memory. For example, the distribution function $f_i(x, t)$ is stored with index $(i + 9 \times x + 9 \times x \times y)$ for the D2Q9 lattice model, as illustrated in Fig. 3. However, as GPUs adopt single instruction multiple threads (SIMT) execution model, the data layout should be changed to structure of array (SoA) to meet the requirement of coalescing memory access in OpenACC based LB implementation. For the D2Q9 lattice model, the distribution function $f_i(x, t)$ is then stored with index $(x + Nx \times y + Nx \times Ny + i)$, so that parallel threads running the same instruction can access consecutive locations in memory. Using Fortran programming language, this index formula implementation means changing array $f(i, x, y)$ to array $f(x, y, i)$; while the array $f[i][y][x]$ is changed to array $f[i][y][x]$ using C programming language. Similar index formula for the D3Q19 lattice model can be straightforwardly obtained.

Fig. 4 compares the parallel performance of OpenACC accelerated LB implementation adopting AoS and SoA data layout. A speedup of 2.37–2.85X can be obtained after changing the data layout, which also means around 29–38 times speedup can be obtained comparing with the original code running on CPU. It is encouraging to see the effort of optimizing data layout, which practically means just changing the index of an array for distribution function and requires little programming effort, rewards nearly a threefold increase in computing performance.

3.3. Minimize memory access frequency

Accessing data in the GPU memory space may take longer time than the actual computations on these data. Thus, it is essential to minimize the frequency of accesses to global memory. In LB method, the frequency of global memory accesses can be reduced by fusing the collision and streaming subroutines. Based on the standard LB implementation described in Section 3.1, there is one read-access and one write-access in each of the two subrouti-
nes to update the distribution function. An alternative implementation is fusing the collision and streaming subroutines, then only one read-access and one write-access is needed in total. Specifically, at odd time steps, the distribution function $f$ is read from the memory and the post-collision distribution function $f'$ is written to the memory. At even time steps, the procedure is reversed. In practical implementation, we suggest to follow the flow chart shown in Fig. 5, which can avoid handling the algorithm flow control to distinguish odd or even iterations using if statement.

Fig. 6 compares the parallel performance between native two-steps and fusion one-step implementations for the update of distribution function. A speedup of 1.34–1.42X can be obtained after reducing memory access frequency, which also means around 39–54 times speedup can be obtained comparing with the original code running on CPU. One should keep in mind that the results in Figs. 2, 4 and 6 represent an incremental improvement in the implementation, and the left side of the bar in Figs. 4 and 6 are the same as the right side of the bar in Figs. 2 and 4, respectively.

It is also interesting to notice from the above performance comparison that MLUPS is higher when the mesh size is above $1000^2$, as shown in Fig. 7 which consolidates the above-mentioned improvement strategies. This is because there is extensive computational load with a larger mesh size and GPUs can hide latency with intensive computations. In addition, the speedup for double diffusive cavity problem degrades a little compared with that for lid driven cavity problem, which is due to the increase of complexity of the numerical algorithm.

### 3.4. Adjust the number of gangs and vector length

In addition to loop directive to parallelize computational intensive loops, OpenACC execution model gives more detailed control over three levels of parallelism via gang, worker, and vector clauses. Gang parallelism is the highest level, and gangs work independently of each other and may not synchronize; vector parallelism has the finest granularity, indicating the data elements that operated on with the same instruction; worker parallelism sits between gang and vector levels. To further boost the parallel performance of the code based on OpenACC acceleration, the programmers may specify the number of gangs and vector length to fit a target architecture. Since the present numerical tests are performed on NVIDIA® Tesla® K20c GPU accelerator, which prefers the number of gangs and vector length to be a multiple of 32, Fig. 8 gives the parallel performance by varying the number of gangs between 27 and 211, and vector length between 27 and 210. Here, we tested five different mesh sizes with the same total computational loads, but with different aspect ratios including 1:16, 1:4, 1:1, 4:1, and 16:1. Results show that an optimal choice for the number of gangs equals 2048, and the vector length equals 1024; in addition, the aspect ratio of the computational domain has minor effects on the parallel performance.

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**Fig. 5.** Schematic illustration of LB flow chat by fusing collision and streaming subroutine.

**Fig. 6.** Performance comparisons between AoS and SoA data layout.

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As a summary, Table 1 gives the maximize parallel performance of OpenACC accelerated LB algorithm implementations by adopting the above-mentioned improvements. The mesh size is 2048/C2, and MLUPS for GPU implementations are chosen after adjusting the number of gangs and vector length on NVIDIA Tesla K20c accelerator. A speedup around 49–64 times can be achieved compared with the serial implementations.

4. Numerical benchmark

4.1. Lid driven cavity problem

The flow domain is a unit square, with the top wall moving at a constant velocity (U0), and the other three walls are stationary. The dimensionless number characterize the system is the Reynolds number (Re), which is defined as

\[ \text{Re} = \frac{U_0 L_0}{v} \]  

where \( U_0 \) is the characteristic velocity and \( L_0 \) is the characteristic length of the system. In this work, we provide results for steady states with Re = 5000 and 7500. The criterion for reaching steady state is given by

\[ \frac{\sum \|u(x, t + 2000 \delta t) - u(x, t)\|_2}{\sum \|u(x, t)\|_2} < 10^{-9} \]  

where \( \|u\|_2 \) denotes \( L^2 \) norm of \( u \). The characteristic velocity is chosen as \( U_0 = 0.1 \). Fig. 9 shows stream-function, vorticity and pressure fields obtained on grid 2049^2, which qualitatively agrees with previous study. We also provide benchmark results on the extreme of stream-function (\( |\psi|_{\text{max}} \)), and the vorticity (\( |\omega| \)) at the same position for both the primary vortex and the lower-right secondary vortex, as shown in Table 2. Existing data from Ghia et al. [26] using vorticity-stream function formulation together with coupled strongly implicit multigrid method; Bruneau et al. [27] using finite differences discretization and on a multigrid solver with a cell-by-cell relaxation procedure; and Zhu et al. [32] using discrete unified gas kinetic scheme are also provided as comparison. In addition, the asymptotic values \( f_{\infty} \) are used as the reference values to compute the relative error, which are then used to estimate the order of accuracy n for LB simulation.

It should be noted that there are controversy results on the Reynolds number when the first Hopf bifurcation occurs: Ghia et al. [26] provided steady results up to \( \text{Re} = 10,000 \), while Bruneau et al. [27] obtained the first Hopf bifurcation at Reynolds number close to \( \text{Re} = 8000 \). Our data shows at \( \text{Re} = 10,000 \) the solution cannot converge to steady states, thus, steady solution of Reynolds number up to \( \text{Re} = 7500 \) are provided as benchmark. It is also worth mentioning that the simulation accuracy can be further...
improved by adopting adaptive mesh refinement method [33,34], however, using non-uniform meshes may spoil the parallel efficiency of LB algorithm and the trade-offs deserve further investigations.

4.2. Buoyancy driven cavity problem

The flow domain is a unit square, with left and right vertical walls maintained at a constant high temperature and low temperature, respectively; and the top and bottom horizontal walls are adiabatic. All four walls are stationary. The dimensionless numbers

<table>
<thead>
<tr>
<th>Problem</th>
<th>CPU (MLUPS)</th>
<th>GPU (MLUPS)</th>
<th>Speedup</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lid driven cavity problem</td>
<td>7.6</td>
<td>488.7</td>
<td>64X</td>
</tr>
<tr>
<td>Buoyancy driven cavity problem</td>
<td>5.3</td>
<td>282.6</td>
<td>53X</td>
</tr>
<tr>
<td>Double diffusive cavity problem</td>
<td>4.3</td>
<td>210.8</td>
<td>49X</td>
</tr>
</tbody>
</table>

Fig. 8. Performance comparisons between various number of gangs and vector length. Five different mesh sizes are tested: red circles represent mesh size $512 \times 8192$; yellow circles represent mesh size $1024 \times 4096$; blue circles represent mesh size $2048 \times 2048$; green circles represent mesh size $4096 \times 1024$; black circles represent mesh size $8192 \times 512$. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

Fig. 9. From left to right: steady solution of stream-function, vorticity and pressure fields on grid 2049 $\times$ 2049.
characterize the system is the thermal Rayleigh number ($Ra_T$) and Prandtl number ($Pr$), which are defined as

$$Ra_T = \frac{g\beta_D\Delta T L_0^3}{\nu\kappa}, \quad Pr = \frac{\nu}{\kappa}$$

where $L_0$ is the characteristic length of the system. In this work, we provide results for steady states with $Ra_T = 10^7$ and $10^8$. The Prandtl number is fixed as $Pr = 0.71$. The criterion for reaching steady state is given by

$$\sum_N\|\mathbf{u}(x_i, t + 2000\delta_t) - \mathbf{u}(x_i, t)\|_2 < 10^{-9},$$
$$\sum_N\|T(x_i, t + 2000\delta_t) - T(x_i, t)\| < 10^{-7}$$

where $\|\mathbf{u}\|_2$ denotes $L^2$ norm of $\mathbf{u}$. Fig. 10 shows stream-function, temperature and vorticity fields obtained on grid 2049$^2$, which qualitatively agrees with previous study.

We also provide benchmark results on the stream-function at the cavity center $|\psi|_{\text{mid}}$, the maximum horizontal velocity $u_{\text{max}}$ and its position $y$ along the vertical mid-plane, the maximum vertical velocity $v_{\text{max}}$ and its position $x$ along the horizontal mid-plane, as shown in Table 3. Existing data from Quéré [28] using pseudo-spectral Chebyshev algorithm; and Contrino et al. [29] using multiple-relaxation-time LB method are also provided as comparison.

In addition to the benchmark result for hydrodynamic intensities, we also provide benchmark results for Nusselt numbers, including the volume average Nusselt number $Nu_v$, the average Nusselt number along the hot wall $Nu_0$, the average Nusselt number along the vertical mid-plane $Nu_1$, the maximum global Nusselt number along the hot wall $Nu_{\text{max}}$ and its location $y$, and the minimum local Nusselt number along the hot wall $Nu_{\text{min}}$, as shown in Table 4.

### 4.3. Double diffusive cavity problem

The flow domain is a unit square, with left vertical walls maintained at a constant high temperature and low concentration; and right vertical walls maintained at a constant low temperature and

![Fig. 10. From left to right: steady solution of stream-function, temperature and vorticity fields on grid 2049 x 2049.](image-url)
The criterion for reaching steady state is given by

\[ Ra_t = \frac{g \beta_i \Delta T L^3}{\nu K}, \quad Ra_s = \frac{g \beta_i \Delta C L^3}{D} \]

where \( L_0 \) is the characteristic length of the system. In this work, we provide results for steady states with \( Ra_t = 5 \times 10^7, 10^8 \), and \( 10^9 \) for \( Ra_t = 10^7; Ra_t = 5 \times 10^7 \) and \( 2 \times 10^8 \) for \( Ra_t = 10^8 \). The Prandtl number is fixed as \( Pr = 0.71 \), and the Lewis number is fixed as \( Le = 1.0 \). The criterion for reaching steady state is given by

\[
\frac{\sum ||u(x, t + 2000\Delta t) - u(x, t)||^2}{\sum ||u(x, t)||^2} < 10^{-9},
\]

\[
\frac{\sum ||T(x, t + 2000\Delta t) - T(x, t)||}{\sum ||T(x, t)||} < 10^{-7},
\]

\[
\frac{\sum ||C(x, t + 2000\Delta t) - C(x, t)||}{\sum ||C(x, t)||} < 10^{-7}
\]

where \( ||u||^2 \) denotes \( L^2 \) norm of \( u \). Figs. 11 and 12 shows stream-function, temperature and concentration fields obtained on grid 2049^2 for \( Ra_t = 10^7 \) and \( Ra_t = 10^8 \), respectively.

We also provide benchmark results for Sherwood numbers, including the volume average Sherwood number (\( Sh \)), the average Sherwood number along the low concentration wall \( Sh_0 \), the average Sherwood number along the vertical mid-plane \( Sh_{1/2} \), the maximum local Sherwood number along the low concentration wall \( Sh_{max} \), and the minimum local Sherwood number along the low concentration wall \( Sh_{min} \) as shown in Tables 5 and 6. Existing data from Beghein et al. [30] using finite volume method with SIMPLER algorithm; and Hu et al. [31] using lattice Boltzmann flux scheme are also provided as a comparison. It is worth mentioning that previous benchmark results on the double diffusive cavity problem is quite limited, e.g., only the average Sherwood number along the low concentration wall \( Sh_0 \) is available; and there is no results are available for \( Ra_t \) up to \( 10^9 \). The present quantitative results will certainly enrich our knowledge on the double diffusive cavity problem, and we encourage follow up works to provide validation using other advanced numerical techniques.

### Table 3
Benchmark solutions of the hydrodynamic intensities.

| RaT | Ref. | Grid | \( |u|_{\text{mid}} \) | \( u_{\text{max}} \) | \( y \) | \( P_{\text{max}} \) | \( x \) |
|-----|------|------|-----------------|-----------------|---|-----------------|------|
| \( 10^7 \) | Quéré [28] | 128^2 | 29.3617 | 148.5954 | 0.879 | 699.1795 | 0.021 |
| | Contrino [29] | 2043^2 | 29.3653 | 148.5852 | 0.8793 | 699.3224 | 0.0213 |
| | Present | 513^2 | 29.37105 | 148.31041 | 0.88012 | 698.7033 | 0.02047 |
| | Present | 1025^2 | 29.3646 | 148.52300 | 0.87951 | 699.2572 | 0.02098 |
| | Present | 2049^2 | 29.36267 | 148.57189 | 0.87921 | 699.3394 | 0.02123 |
| | \( \infty \) | 29.36202 | 148.58821 | 0.87911 | 699.3668 | 0.02131 |
| | \( n \) | 1.90 | 2.05 | 1.67 | 2.30 | 1.67 |
| \( 10^8 \) | Quéré [28] | 128^2 | 52.32 | 321.9 | 0.928 | 2222. | 0.012 |
| | Contrino [29] | 2043^2 | 52.3508 | 321.9063 | 0.9279 | 2222.3279 | 0.012 |
| | Present | 513^2 | 52.37456 | 310.43507 | 0.91910 | 2219.0321 | 0.01267 |
| | Present | 1025^2 | 52.33688 | 318.34510 | 0.92634 | 2222.3104 | 0.01220 |
| | Present | 2049^2 | 52.32652 | 320.98831 | 0.92753 | 2223.4660 | 0.01196 |
| | \( \infty \) | 52.32306 | 321.87064 | 0.92793 | 2223.8517 | 0.01188 |
| | \( n \) | 1.95 | 2.24 | 2.24 | 2.24 | 2.10 |

### Table 4
Benchmark solutions of the Nusselt numbers.

<table>
<thead>
<tr>
<th>RaT</th>
<th>Ref.</th>
<th>Grid</th>
<th>( Nu )</th>
<th>( Nu_0 )</th>
<th>( Nu_{1/2} )</th>
<th>( Nu_{\text{max}} )</th>
<th>( Nu_{\text{min}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>( \infty )</td>
<td>16.52328</td>
<td>16.52190</td>
<td>16.52334</td>
<td>39.37374</td>
<td>1.36572</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( n )</td>
<td>1.97</td>
<td>2.39</td>
<td>1.97</td>
<td>2.13</td>
<td>2.10</td>
<td></td>
</tr>
<tr>
<td>( 10^8 )</td>
<td>Quéré [28]</td>
<td>128^2</td>
<td>( 30.225 )</td>
<td>30.225</td>
<td>87.24</td>
<td>1.919</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Contrino [29]</td>
<td>2043^2</td>
<td>30.2241</td>
<td>30.2251</td>
<td>87.2454</td>
<td>1.9195</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Present</td>
<td>513^2</td>
<td>30.30100</td>
<td>30.31372</td>
<td>30.30588</td>
<td>88.8534</td>
<td>2.12199</td>
</tr>
<tr>
<td></td>
<td>Present</td>
<td>1025^2</td>
<td>30.24443</td>
<td>30.24571</td>
<td>30.24671</td>
<td>88.6161</td>
<td>1.97001</td>
</tr>
<tr>
<td></td>
<td>Present</td>
<td>2049^2</td>
<td>30.23013</td>
<td>30.23050</td>
<td>30.23050</td>
<td>87.49182</td>
<td>1.93027</td>
</tr>
<tr>
<td></td>
<td>( \infty )</td>
<td>30.22536</td>
<td>30.22542</td>
<td>30.22542</td>
<td>87.11660</td>
<td>1.91701</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( n )</td>
<td>1.99</td>
<td>2.15</td>
<td>1.99</td>
<td>2.09</td>
<td>1.98</td>
<td></td>
</tr>
</tbody>
</table>

5. Conclusion

In this work, we have presented improved implementation of OpenACC to accelerate LB simulations involving fluid flow, heat and mass transfer. The results demonstrate that using OpenACC allows a speed up around 50–60 times for multiphysics LB simulation. The applications of OpenACC accelerated LB simulation to two-dimensional lid driven cavity problem, buoyancy driven cavity problem, and double diffusive cavity problem using fine grid provide benchmark quality results. The extensions to much more memory consuming three-dimensional implementation will be pursued in future work.
Fig. 11. From left to right: steady solution of stream-function, temperature and concentration fields on grid 2049 × 2049 ($Ra_T = 10^7$).

(a) $Ra_x = 5 \times 10^6$

(b) $Ra_x = 5 \times 10^7$

(c) $Ra_x = 10^8$

Fig. 12. From left to right: steady solution of stream-function, temperature and concentration fields on grid 2049 × 2049 ($Ra_T = 10^7$).

(a) $Ra_x = 5 \times 10^7$

(b) $Ra_x = 2 \times 10^8$

Table 5
Benchmark solutions of the Sherwood numbers ($Ra_t - 10^9$).

<table>
<thead>
<tr>
<th>$Ra_t$</th>
<th>Ref</th>
<th>Grid</th>
<th>$\langle Sh \rangle$</th>
<th>$Sh_0$</th>
<th>$Sh_{1/2}$</th>
<th>$Sh_{max}$</th>
<th>$Sh_{max}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$5 \times 10^9$</td>
<td>Beghein [30]</td>
<td>45$^2$</td>
<td>–</td>
<td>–13.6</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Hu [31]</td>
<td>200$^2$</td>
<td>–</td>
<td>–13.64</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>$\infty$</td>
<td>n</td>
<td>1.96</td>
<td>2.73</td>
<td>1.95</td>
<td>1.79</td>
<td>3.10</td>
<td></td>
</tr>
<tr>
<td>$5 \times 10^7$</td>
<td>Beghein [30]</td>
<td>45$^2$</td>
<td>–</td>
<td>–23.7</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Hu [31]</td>
<td>200$^2$</td>
<td>–</td>
<td>–23.85</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>$\infty$</td>
<td>n</td>
<td>1.99</td>
<td>2.19</td>
<td>1.99</td>
<td>1.92</td>
<td>2.20</td>
<td></td>
</tr>
<tr>
<td>$\infty$</td>
<td>n</td>
<td>1.99</td>
<td>2.16</td>
<td>1.99</td>
<td>1.95</td>
<td>2.15</td>
<td></td>
</tr>
</tbody>
</table>

Table 6
Benchmark solutions of the Sherwood numbers ($Ra_t - 10^8$).

<table>
<thead>
<tr>
<th>$Ra_t$</th>
<th>Ref</th>
<th>Grid</th>
<th>$\langle Sh \rangle$</th>
<th>$Sh_0$</th>
<th>$Sh_{1/2}$</th>
<th>$Sh_{max}$</th>
<th>$Sh_{max}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$5 \times 10^7$</td>
<td>Present</td>
<td>513$^2$</td>
<td>–25.29378</td>
<td>–25.29600</td>
<td>–25.29527</td>
<td>–1.71943</td>
<td>–69.42192</td>
</tr>
<tr>
<td>$\infty$</td>
<td>n</td>
<td>1.99</td>
<td>2.18</td>
<td>1.98</td>
<td>1.91</td>
<td>2.24</td>
<td></td>
</tr>
<tr>
<td>$2 \times 10^8$</td>
<td>Present</td>
<td>513$^2$</td>
<td>–30.30208</td>
<td>–30.31536</td>
<td>–30.30706</td>
<td>–1.88324</td>
<td>–89.30962</td>
</tr>
<tr>
<td>$\infty$</td>
<td>n</td>
<td>2.00</td>
<td>2.16</td>
<td>2.00</td>
<td>1.96</td>
<td>2.11</td>
<td></td>
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</tbody>
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Acknowledgements

The authors thank Professor Wei Shyy for his useful discussion. The work described in this paper was fully supported by a grant from the Research Grants Council of the Hong Kong Special Administrative Region, China (Project No. 623331).

Appendix A. D2Qn lattice model

A.1. D2Q9 lattice model

For the two-dimensional D2Q9 lattice model, $\mathbf{e}_i$ can be given as

$$
\begin{bmatrix}
0 & 1 & -1 & 0 & 0 & 1 & -1 & 1 & -1 \\
0 & 0 & 1 & -1 & 1 & -1 & 1 & -1 & -1
\end{bmatrix}
$$

$M$ is a $9 \times 9$ orthogonal transformation matrix given by [35]

A.2. D2Q5 lattice model

For the two-dimensional D2Q5 lattice model, $\mathbf{e}_i$ can be given as

$$
\begin{bmatrix}
0 & 1 & -1 & 0 & 0 \\
0 & 0 & 0 & 1 & -1
\end{bmatrix}
$$

$N$ is a $5 \times 5$ orthogonal transformation matrix given by [36]
Appendix B. Dimensional scaling

B.1. Nondimensionalization model for fluid flow

With the scalings
\[ x/L_0 \rightarrow \xi, \quad t/\left( L_0^2 / U_0 \right) \rightarrow \tau, \quad u/U_0 \rightarrow \tilde{u}, \]
\[ p/\left( \rho_0 U_0^2 / L_0^2 \right) \rightarrow \tilde{p}, \quad \rho/\left( \rho_0 L_0^2 \right) \rightarrow \tilde{\rho}. \]
(31)

then, Eqs. (1a) and (1b) can be rewritten in dimensionless form as
\[ \nabla \cdot \tilde{u} = 0 \]
(32a)
\[ \frac{\partial \tilde{u}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{u} = -\nabla \tilde{p} + \frac{1}{Re} \nabla^2 \tilde{u} \]
(32b)

B.2. Nondimensionalization model for fluid flow and heat transfer

With the scalings
\[ x/L_0 \rightarrow \xi, \quad t/\left( L_0^2 / K \right) \rightarrow \tau, \quad u/\left( K / L_0 \right) \rightarrow \tilde{u}, \]
\[ p/\left( \rho_0 K^2 / L_0^2 \right) \rightarrow \tilde{p}, \quad (T - T_0) / \Delta T \rightarrow \tilde{T} \]
(33)

then, Eqs. 6a, 6b and 6c can be rewritten in dimensionless form as
\[ \nabla \cdot \tilde{u} = 0 \]
(34a)
\[ \frac{\partial \tilde{u}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{u} = -\nabla \tilde{p} + Pr \nabla^2 \tilde{u} + Ra \tilde{T} \tilde{y} \]
(34b)
\[ \frac{\partial \tilde{T}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{T} = \nabla^2 \tilde{T} \]
(34c)

B.3. Nondimensionalization model for fluid flow, heat transfer and mass transfer

With the scalings
\[ x/L_0 \rightarrow \xi, \quad t/\left( L_0^2 / K \right) \rightarrow \tau, \quad u/\left( K / L_0 \right) \rightarrow \tilde{u}, \quad p/\left( \rho_0 K^2 / L_0^2 \right) \rightarrow \tilde{p}, \]
\[ (T - T_0) / \Delta T \rightarrow \tilde{T}, \quad (C - C_0) / \Delta C \rightarrow \tilde{C} \]
(35)

then, Eqs. (15a)-(15c) and (15d) can be rewritten in dimensionless form as
\[ \nabla \cdot \tilde{u} = 0 \]
(36a)
\[ \frac{\partial \tilde{u}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{u} = -\nabla \tilde{p} + Pr \nabla^2 \tilde{u} + Ra \tilde{T} \tilde{D} + Ra \tilde{C} \tilde{D} \]
(36b)
\[ \frac{\partial \tilde{T}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{T} = \nabla^2 \tilde{T} \]
(36c)
\[ \frac{\partial \tilde{C}}{\partial \tau} + \tilde{u} \cdot \nabla \tilde{C} = \frac{1}{Le} \nabla^2 \tilde{C} \]
(36d)